



Probabilistic Model Checking in Practice

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Overview

- Tool support for probabilistic model checking
- The PRISM model checker
 - functionality, features
 - modelling language
 - property specification
- PRISM tool demo
- PRISM lab session

Probabilistic model checking

- Recap...
- Probabilistic models
 - discrete-time Markov chains (DTMCs)
 - Markov decision processes (MDPs)
 - continuous-time Markov chains (CTMCs)
- Probabilistic temporal logics
 - PCTL, LTL, PCTL* (discrete-time models)
 - CSL (continuous-time models)

Probabilistic model checkers

- **PRISM (this session)**
 - DTMCs, MDPs, CTMCs + costs/rewards
- **Markov chain model checkers**
 - MRMC: explicit-state engine for DTMCs, CTMCs + rewards
 - PEPA Plug-in Project: CSL model checking for PEPA (CTMCs)
 - CASPA: symbolic model checking of stochastic process algebra
- **MDP model checkers**
 - LiQuor: LTL verification for MDPs (Probmela language)
 - RAPTURE: abstraction/refinement tool for MDPs
- **Many other interesting tools being developed:**
 - e.g. for PTAs: UPPAAL PRO, PRISM (soon), mcpta, Fortuna

The PRISM tool

- **PRISM: Probabilistic symbolic model checker**
 - developed at Universities of Birmingham/Oxford, since 1999
 - free, open source (GPL), versions for all major OSs
- **Modelling of:**
 - DTMCs, CTMCs, MDPs + costs/rewards
 - simple, state-based modelling language
- **Model checking of:**
 - PCTL, CSL, LTL, PCTL* + extensions + costs/rewards
- **Features**
 - efficient symbolic/explicit implementation techniques
 - approximate verification using simulation + sampling
 - GUI: model editor, simulator/debugger, result visualisation



PRISM modelling language

- Simple, textual, state-based language
 - modelling of DTMCs, CTMCs and MDPs
 - based on Reactive Modules [Alur/Henzinger]
- Basic components:
 - **modules**: components of system being modelled
 - combined through parallel composition
 - **variables**: local/global, finite-ranging (integers/Booleans)
 - **guarded commands**: probabilistic updates to variables
 - optional action labels for synchronisation

$[send] (s=2) \rightarrow p_{loss} : (s'=3) \& (lost'=lost+1) + (1-p_{loss}) : (s'=4);$

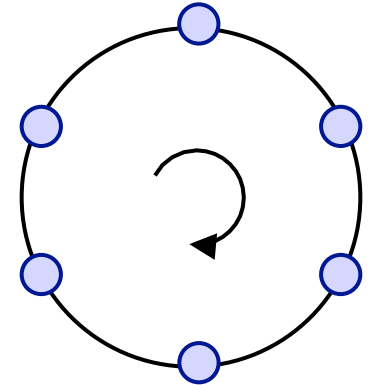


PRISM modelling language

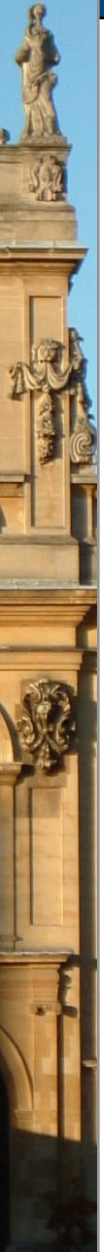
- **Parallel composition**
 - synchronous or asynchronous composition of modules
 - process–algebraic operators for e.g. action hiding/renaming
- **Module renaming**
 - easy construction of identical/symmetric modules
- **Rewards (or equivalently: costs, prices, ...)**
 - real-valued quantities assigned to states and/or transitions
 - these can have a wide range of possible interpretations, e.g.:
 - elapsed time, power consumption, size of message queue, number of messages successfully delivered, net profit, ...

Example: Leader election

- Randomised leader election protocol
 - due to Itai & Rodeh (1990)
- Set-up: N nodes, connected in a ring
 - communication is synchronous (lock-step)
- Aim: elect a leader
 - i.e. one uniquely designated node
 - by passing messages around the ring
- Protocol operates in rounds. In each round:
 - each node chooses a (uniformly) random $id \in \{0, \dots, k-1\}$
 - (k is a parameter of the protocol)
 - all nodes pass their id around the ring
 - the node with the **maximum unique** id becomes the leader
 - if no unique id exists, try again with a new round



PRISM code...

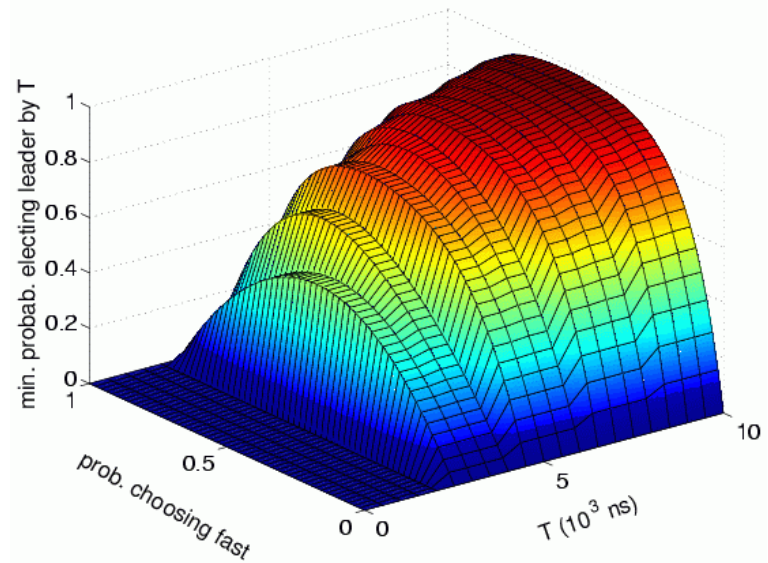
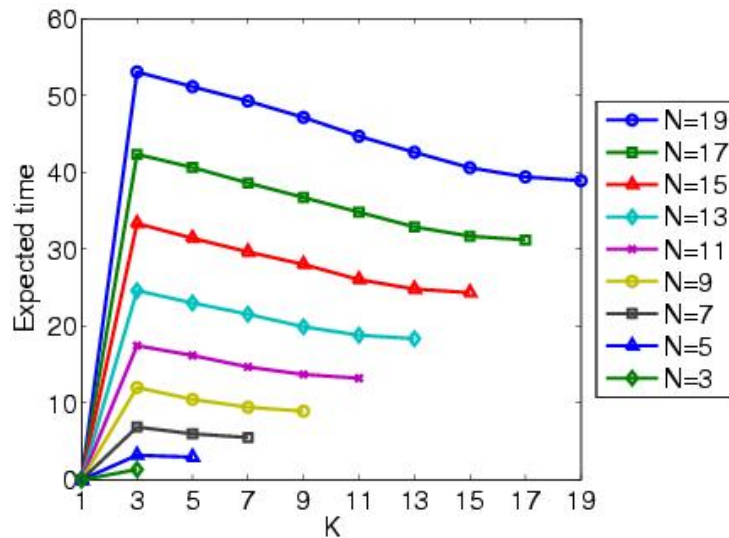


PRISM property specifications

- Based on (probabilistic extensions of) temporal logic
 - incorporates PCTL, CSL, LTL, PCTL*
 - also includes: quantitative extensions, costs/rewards
- Example properties (leader election)
 - $P_{\geq 1} [F \text{ “elected” }]$
”with probability 1, a leader is eventually elected”
 - $P_{\geq 1} [F G \text{ “elected” }]$
”with probability 1, a leader is eventually elected permanently”
 - $P_{>0.8} [F^{\leq T} \text{ “elected” }]$
”with probability > 0.8 , a leader is elected within T steps”
- Usually focus on quantitative properties:
 - $P_{=?} [F^{\leq T} \text{ “elected” }]$
”what is the probability that a leader is elected within T steps?”

PRISM property specifications

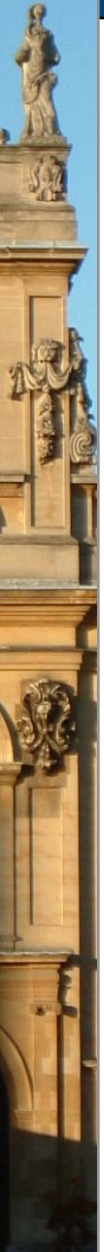
- Experiments:
 - ranges of model/property parameters
 - e.g. $P_{=?} [F^{\leq T} \text{“elected”}]$ for $N=1..5$, $T=1..100$ where N is some model parameter and T a time bound
 - identify patterns, trends, anomalies in quantitative results



PRISM property specifications

- Rewards/costs
 - expected (instantaneous/cumulative) value of reward
 - e.g. “the expected time for a leader to be elected”
 - e.g. “the expected power consumption over one hour”
 - e.g. “the expected queue size after exactly 90 seconds”
- Best/worst-case scenarios
 - combining “quantitative” and “exhaustive” aspects
 - for MDPs, quantification over all adversaries/schedulers
 - e.g. $P_{\min=?} [F \text{ “terminate” }]$ – “worst-case probability of termination over all possible schedulers”
 - for any model, compute values for a range of states
 - e.g. $R_{=?} [F \text{ end } \{ \text{“init”} \} \{ \text{max} \}]$ – “maximum expected run-time over all possible initial configurations”

PRISM demo...



More info on PRISM

- PRISM website: <http://www.prismmodelchecker.org/>
 - tool download: binaries, source code (GPL)
 - on-line example repository (50+ case studies)
 - on-line documentation: manual, tutorial, FAQ
 - support: help forum
 - related publications, talks, tutorials, links
- Practical session using PRISM
 - upstairs in PC labs 2A52 and 2A54
 - <http://www.prismmodelchecker.org/courses/qmc10/>